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13	69	(((((345/418.ccls. or 345/419.ccls.) and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))) and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (mov$5 or motion$4 or travel$4)) and (model or reference)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/03 14:59

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-	742	382/154.ccls.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 14:00
-	145	382/154.ccls. and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:23
-	77	(382/154.ccls. and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))) and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:21
-	73	((382/154.ccls. and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))) and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (mov$5 or motion$4 or travel$4)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 16:02
-	73	(((382/154.ccls. and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))) and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (mov$5 or motion$4 or travel$4)) and (model or reference)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:26
-	6	382/154.ccls. and ((trac$4 near4 point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 16:10
-	1	5616078.pn.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 15:06
-	461	348/169.ccls.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:20
-	226	348/169.ccls. and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:22
-	145	(348/169.ccls. and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (silhouette or outlin$4 or curv$4 or shap$4)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 15:48
-	20	(((348/169.ccls. and ((point$1) near4 (silhouette or outlin$4 or curv$4 or shap$4))) and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (mov$5 or motion$4 or travel$4)) and (model or reference)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 11:34
-	1	5845006.pn.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/02 15:06
-	4	5845006.URPN.	USPAT	2003/07/02 15:07
-	3	("4232968" | "5202928" | "5625702").PN.	USPAT	2003/07/02 15:21

| - | | 52 | (348/169.ccls. and ((detec$5 or sens$4 or measur$5 or inspect$5 or recogniz$4) near4 (position$4 or postur$4 or stanc$4))) and (silhouette or outlin$4 or curv$4 or shap$4) and ((repeat$4 or iterat$4 or loop$4 or reiterat$4) with (imag$4 or window or fram$4)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/07/02 15:52 |

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I-Chen Lin; Jeng-Sheng Yeh; Ming Ouhyoung;
Computer Graphics and Applications, IEEE , Volume: 22 Issue: 6 , Nov.-Dec. 2(
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[Abstract]   [PDF Full-Text (881 KB)] **IEEE JNL**

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2 **Visual specification of robot motion**
Shiu, Y.C.; Chong, R.; Runner, K.; Scaggs, T.; Seth, N.; Craven, R.;
Aerospace and Electronics Conference, 1992. NAECON 1992., Proceedings of th
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3 **3D shape measurement of underwater objects using motion stereo**
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